

High Performance MALDI-TOF Mass Spectrometry

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Outline

- **Goals:**

Design and build MALD-TOF Analyzers Optimized for Selected Applications

- **Approach:**

- Modular construction using common elements
- State-of-the-art technology, e.g. 5 khz laser
- Focus on the needs of the application
- Keep it small, simple, and reliable without sacrificing performance

- **Analyzer geometries**

- Linear for broad mass range and sensitivity at high mass (to 500 kDa).
- **Reflector for high resolution, mass accuracy, and sensitivity at low mass (0.1-5 kDa)**
- Reversed geometry reflector for both resolution and sensitivity in intermediate mass range (1-50 kDa)

- **Optimization Strategy**

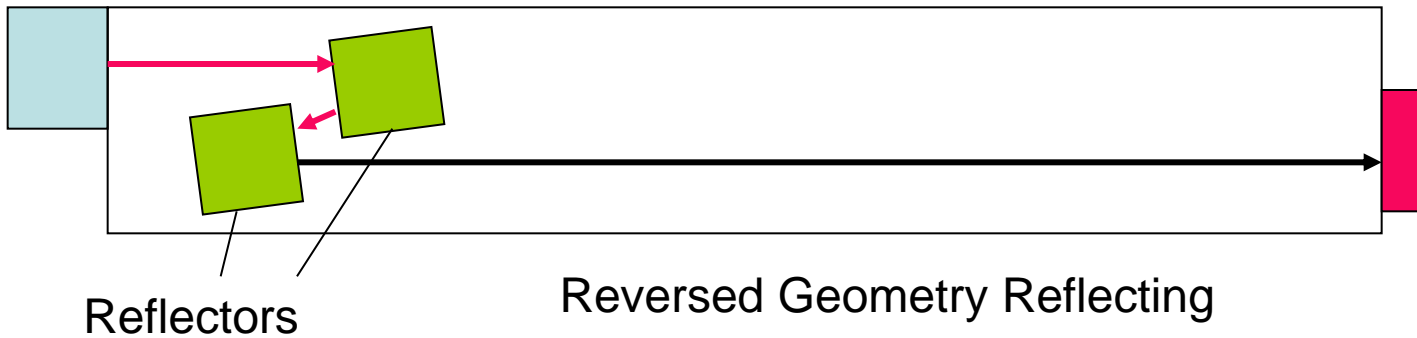
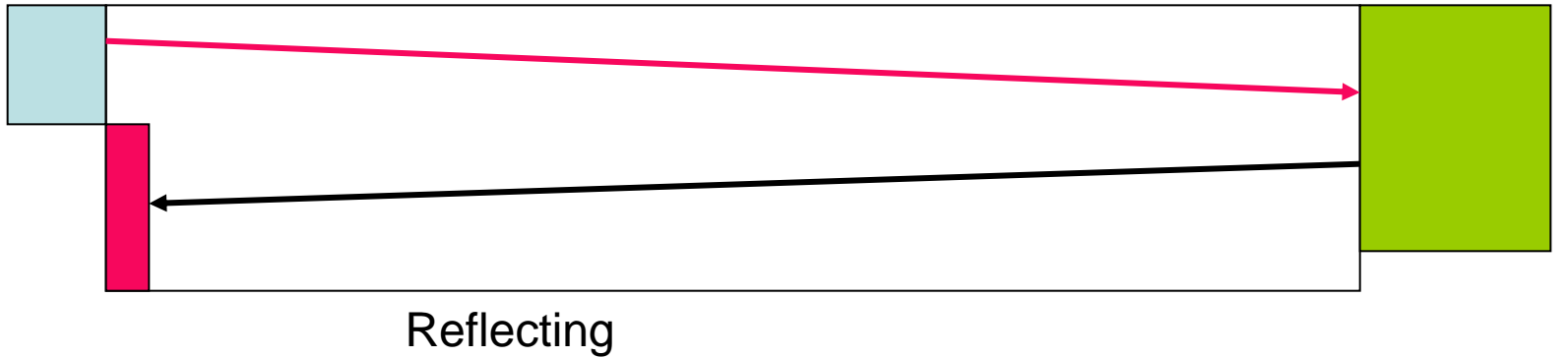
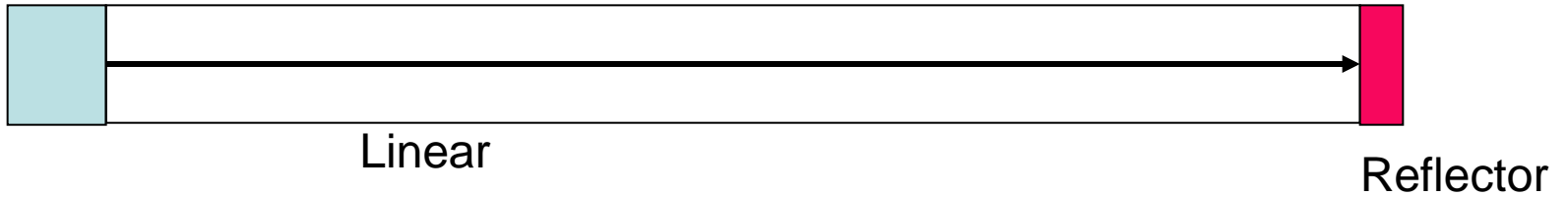
- **Results**

Time-of-flight analyzer geometries

Ion Source

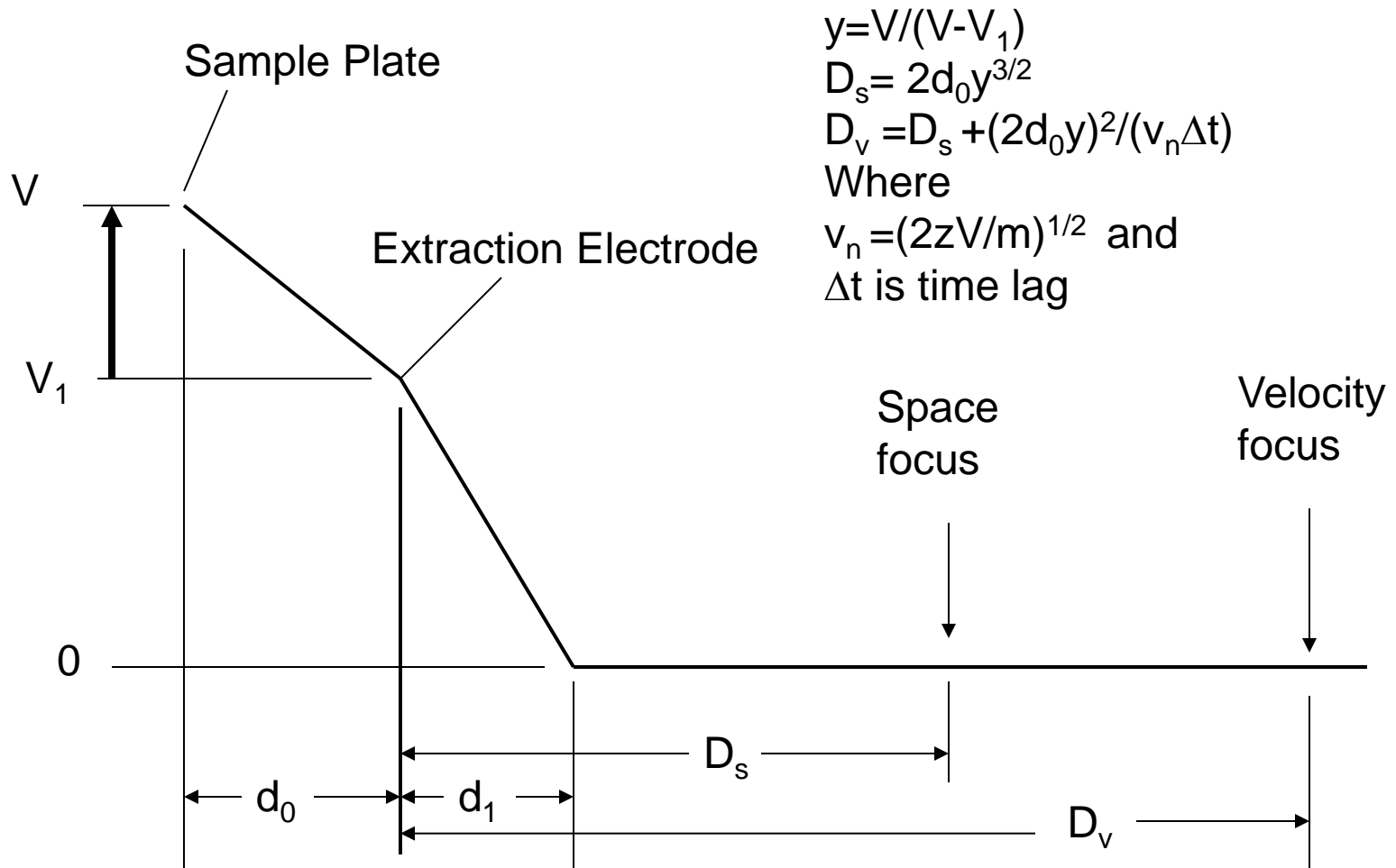
Drift Tube

Detector



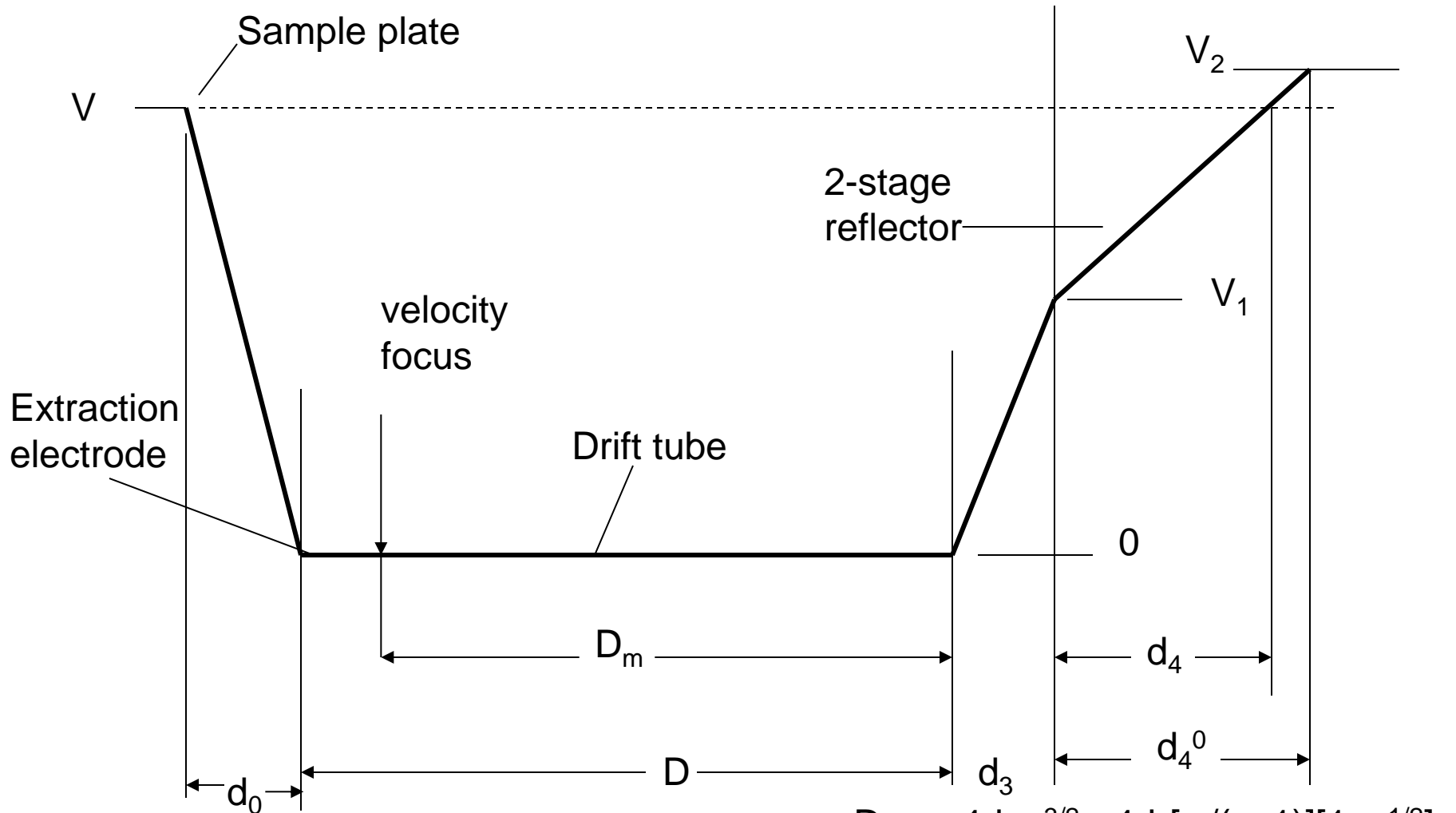
Reflector MS for MALDI mass fingerprinting peptides, metabolites, and other small molecules

- High sensitivity and dynamic range in mass range 0.1-5 kDa
- Highest possible resolving power and mass accuracy (1 ppm RMS)
- High throughput
- Low cost, stable, reliable, and small
- No operator expertise required



For single field source, $V_1 = 0$, $y = 1$
 Simultaneous 1st and 2nd order focus
 $D_v = 6d_0$, $v_n \Delta t = d_0$

Wiley and McLaren
 RSI (1955) 26, 1150-1157
 Vestal and Juhasz
 JASMS (1998) 9, 892-911



Simultaneous 1st and 2nd order focus

$$4d_3/D_m = (w-3)/w$$

$$4d_4/D_m = w^{-3/2} + (4d_3/D_m)/(w + w^{1/2})$$

$$D_{m1} = 4d_4 w^{3/2} + 4d_3 [w/(w-1)] [1-w^{1/2}]$$

$$3D_{m2} = 4d_4 w^{5/2} + 4d_3 [w/(w-1)] [1-w^{3/2}]$$

$$d_4 = d_4^0 (V-V_1)/(V_2-V_1)$$

$$w = V/(V-V_1)$$

Contributions to relative peak width, $\Delta m/m$, with 1st and 2nd order velocity focusing

Initial position, δx : $R_{s1} = 2[(D_v - D_s)/2d_0y](\delta x/D_e)$

Initial velocity, δv_0 : $R_{v1} = (4d_0y/D_e)(\delta v_0/v_n)[(1 - (m/m^*)^{1/2})]$

$$R_{v2} = 2[2d_0y/(D_v - D_s)]^2 (\delta v_0/v_n)^2 = 0$$

$$R_{v3} = 2[2d_0y/(D_v - D_s)]^3 (\delta v_0/v_n)^3$$

$$R_v = R_{v1} + R_{v3}$$

Time error, δt : $R_t = 2\delta t/t = 2\delta t v_n/D_e$

Trajectory error, δL : $R_L = 2\delta L/D_e$

Voltage error, δV : $R_V = \delta V/V$

Resolving power:

$$R^{-1} = [R_{s1}^2 + R_v^2 + R_t^2 + R_L^2 + R_V^2]^{-1/2}$$

Instrument Parameters for Reflecting Analyzer (single-field source and two-field mirror)

$D_e=3200$, $d_0=3$, $D=2264$, $d_3=114.2$, $d_4^0=127.7$ all in mm

$V=8.56$, $V_1=6.31$, $V_2=9.23$ all in kV

$\delta t=1.5$ nsec (0.5 nsec bins, 1 nsec single ion pulse width)

Focus mass $m^*=1.6$ kDa

$D_v=6d_0 = 18$ mm, v_n (for m^*)= 0.03215 mm/nsec

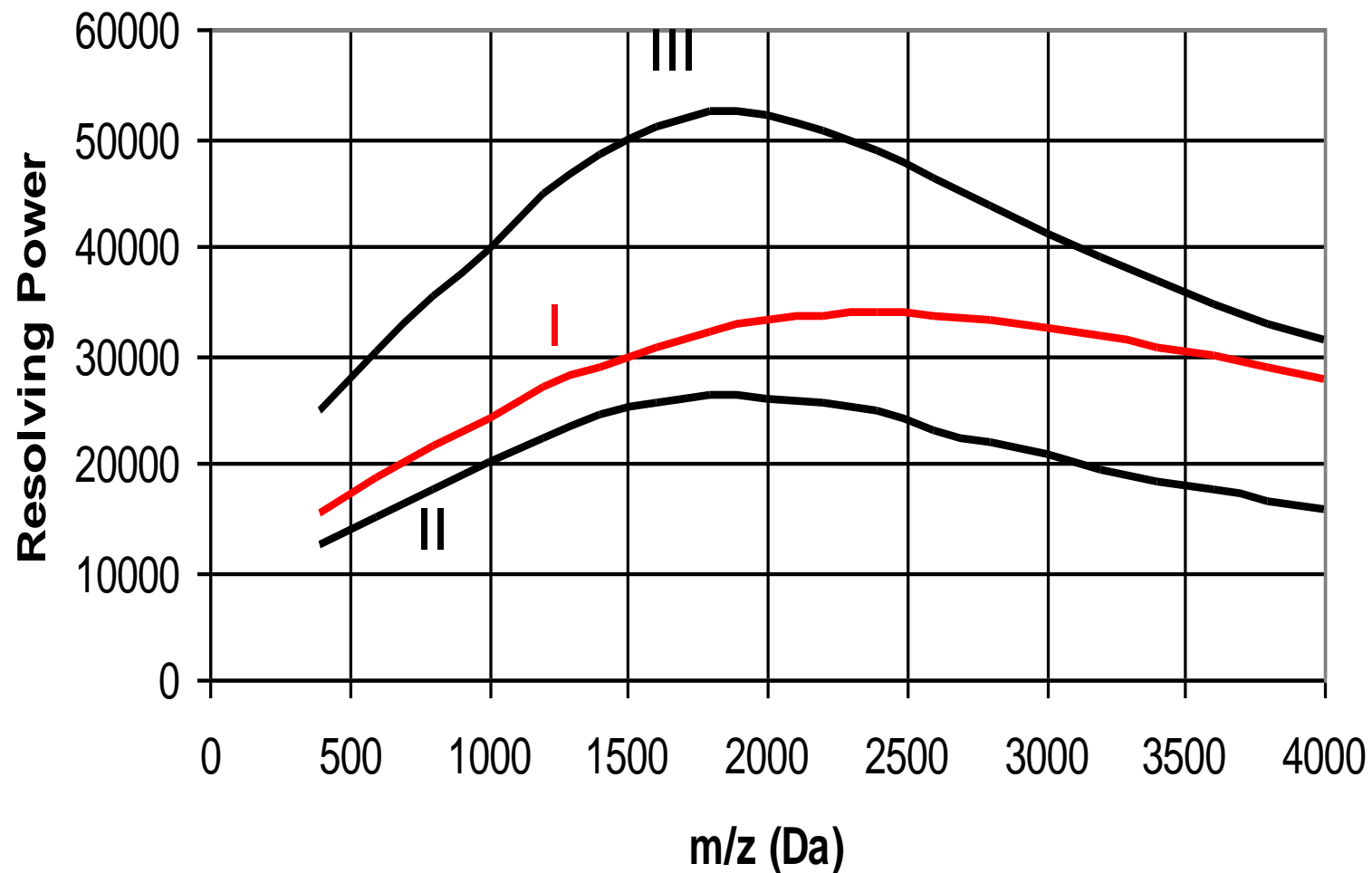
Time lag $\Delta t=d_0/v_n = 93$ nsec

$K=2d_0/(D_v-D_s)=0.5$

Initial Conditions for MALDI (typical)

$\delta v_0=400$ m/sec, $\delta x=0.01$ mm

Trajectory error and voltage error assumed to be small



Calculated resolving power for reflecting analyzer.

$\delta v_0=400\text{m/s}$, $\delta x=0.01\text{ mm}$ for I and III and 800 m/s and 0.02 mm for II.

$\delta t=1.5\text{ nsec}$ for I and II and 0.75 nsec for III,

Conditions for minimizing relative peak width, $\Delta m/m$

Initial position, δx : $R_{s1} = 2\mathbf{K}^{-1}(\delta x/D_e)$

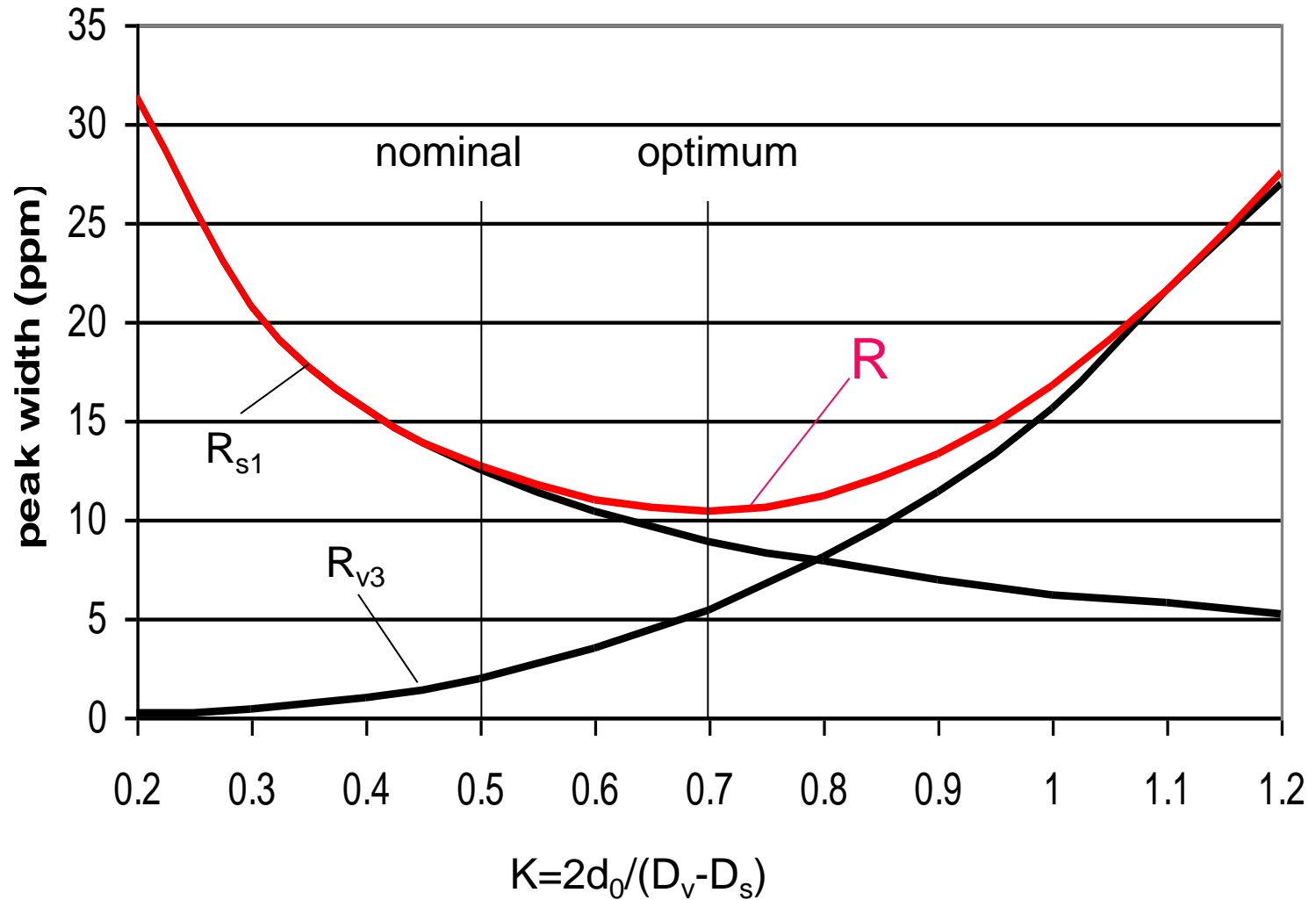
Initial velocity, δv_0 : $R_{v1} = (4d_0y/D_e)(\delta v_0/v_n)[(1-(m/m^*)^{1/2})]$
 $R_{v3} = 2\mathbf{K}^3 (\delta v_0/v_n)^3$
 $R_v = R_{v1} + R_{v3}$

Time error, δt : $R_t = 2\delta t/t = 2\delta t v_n/D_e$

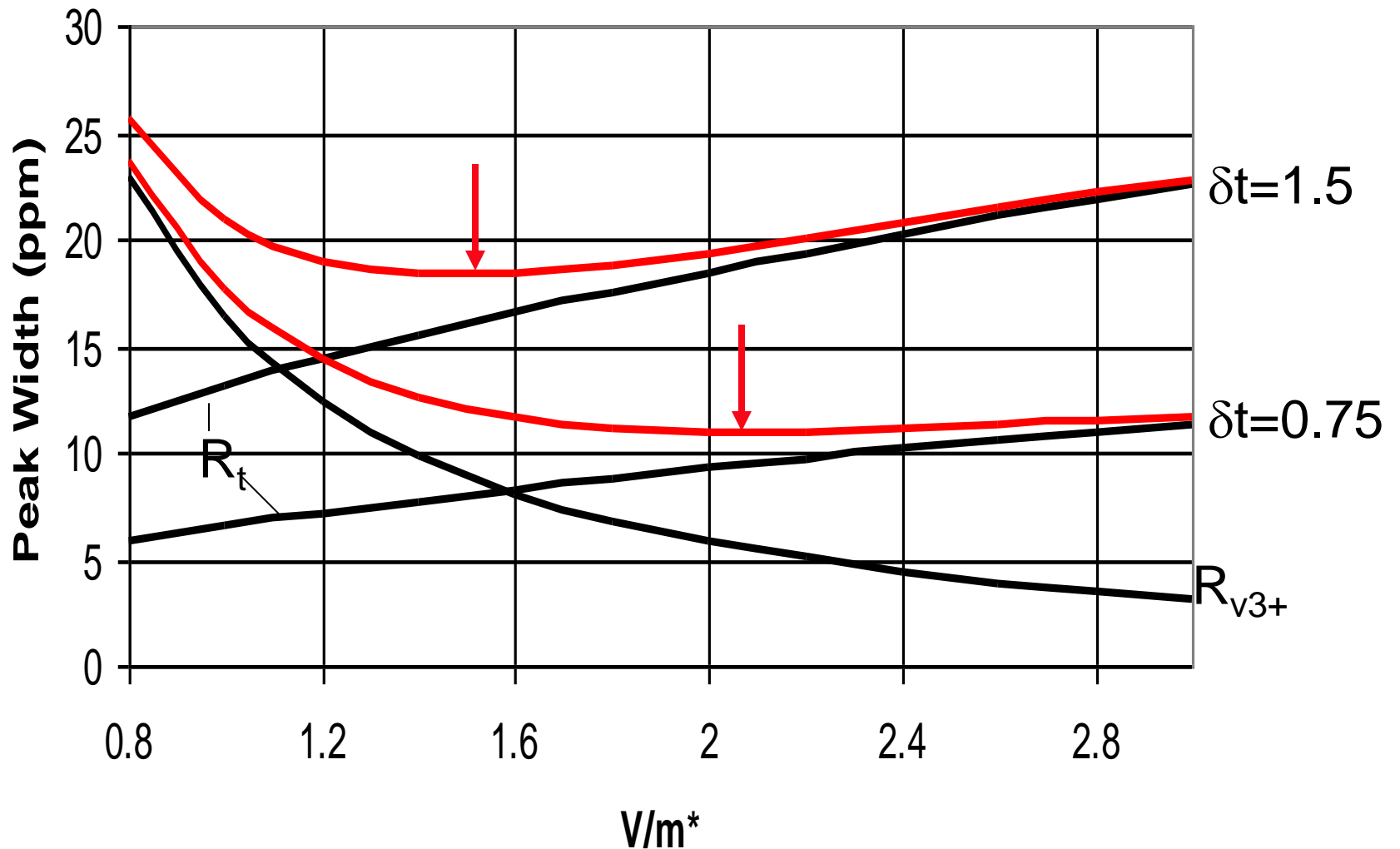
Peak Width: $R = [R_{s1}^2 + R_v^2 + R_t^2 + R_L^2 + R_V^2]^{1/2}$

Optimum focus: $dR/dK = 0$, $K = 2d_0/D_v - D_s$

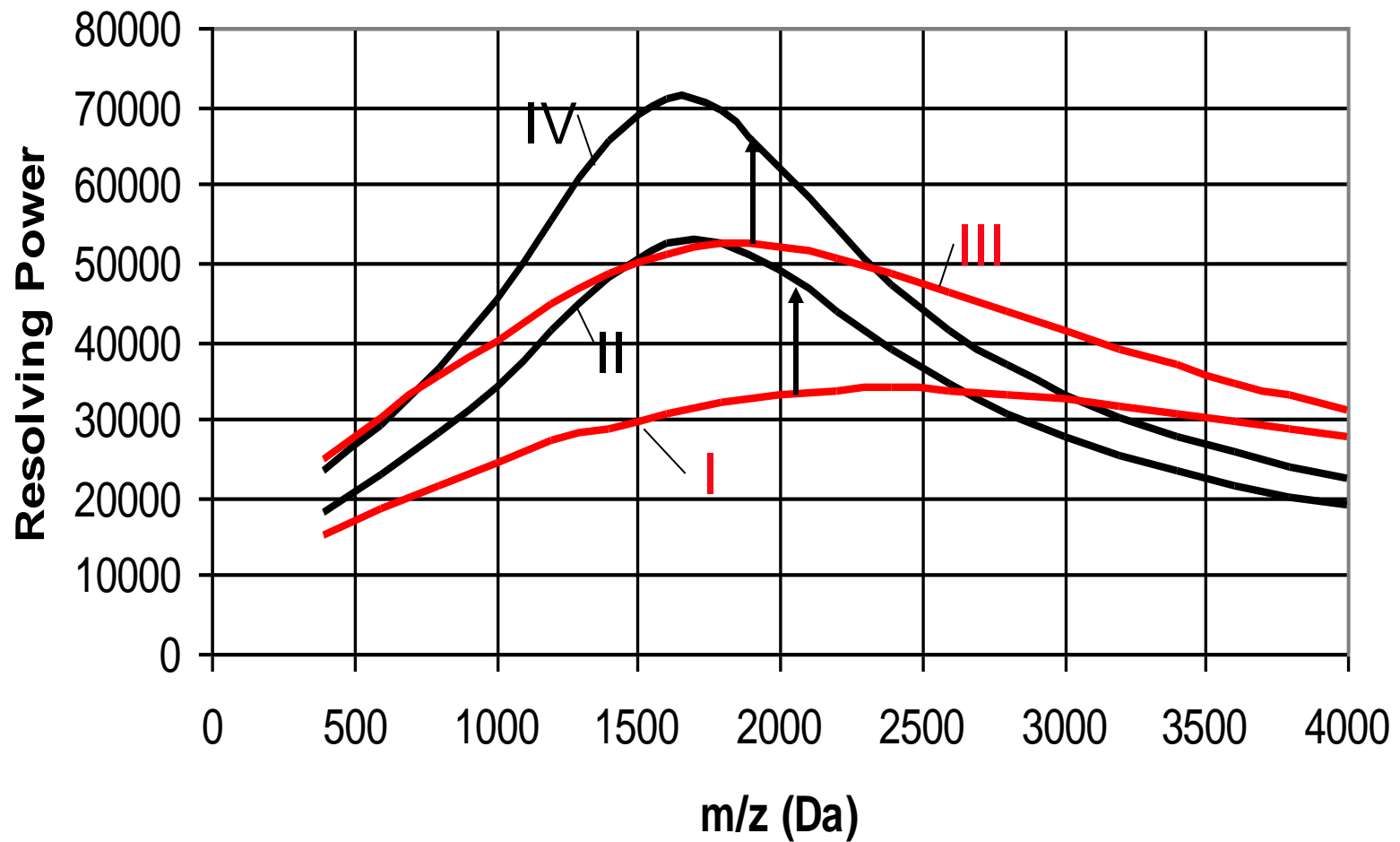
Optimum velocity: $dR/dv_n = 0$, $v_n = C(V/m^*)^{1/2}$
(can be optimized at m^* or any other mass)



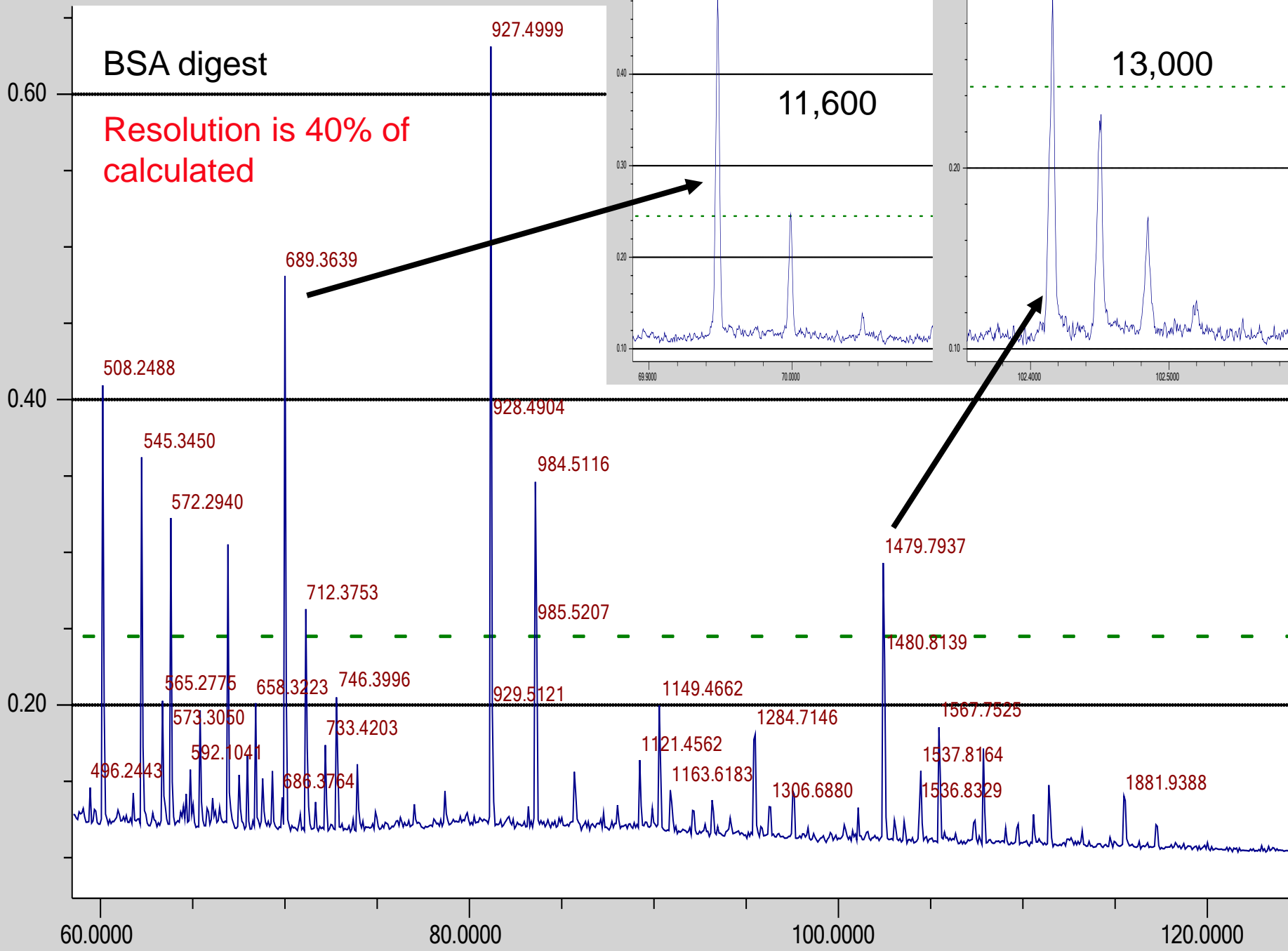
Minimum peak width as function of focusing parameter K .
 Optimum value corresponds to $dR/dK=0$

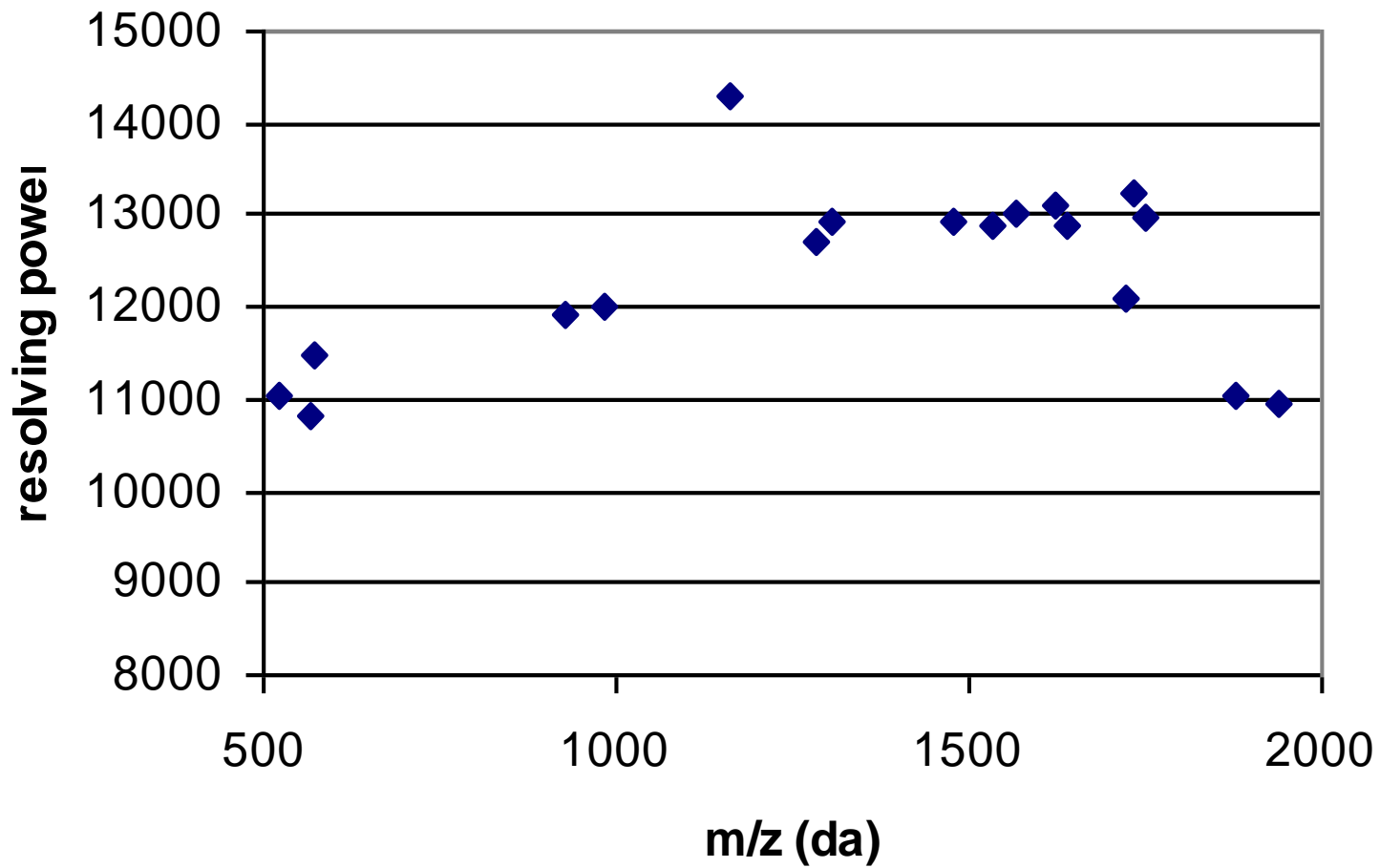


Minimum peak width as function of V/m^* (indicated by arrows for $\delta t = 1.5$ and 0.75 nsec). For $m^* = 1600$ Da optimum voltages are 2.4 and 3.4 kV, respectively.



Optimized resolving power for reflecting analyzer, $\delta v_0=400\text{m/s}$, $\delta x=0.01\text{ mm}$. $\delta t=1.5\text{ nsec}$ for I and II and 0.75 nsec for III and IV. Red lines nominal, black at optimum for focus mass.





Experimental resolving power for reflecting analyzer on BSA digest

Contributions to relative peak width, $\Delta m/m$

Initial position, δx : $R_{s1} = [(D_v - D_s)/D_e](\delta x/d_0 y)$

Initial velocity, δv_0 : $R_{v1} = (4d_0 y/D_e)(\delta v_0/v_n)[(1 - (m/m^*)^{1/2})]$
 $R_{v2} = 2[2d_0 y/(D_v - D_s)]^2 (\delta v_0/v_n)^2$
 $R_{v3} = 2[2d_0 y/(D_v - D_s)]^3 (\delta v_0/v_n)^3$

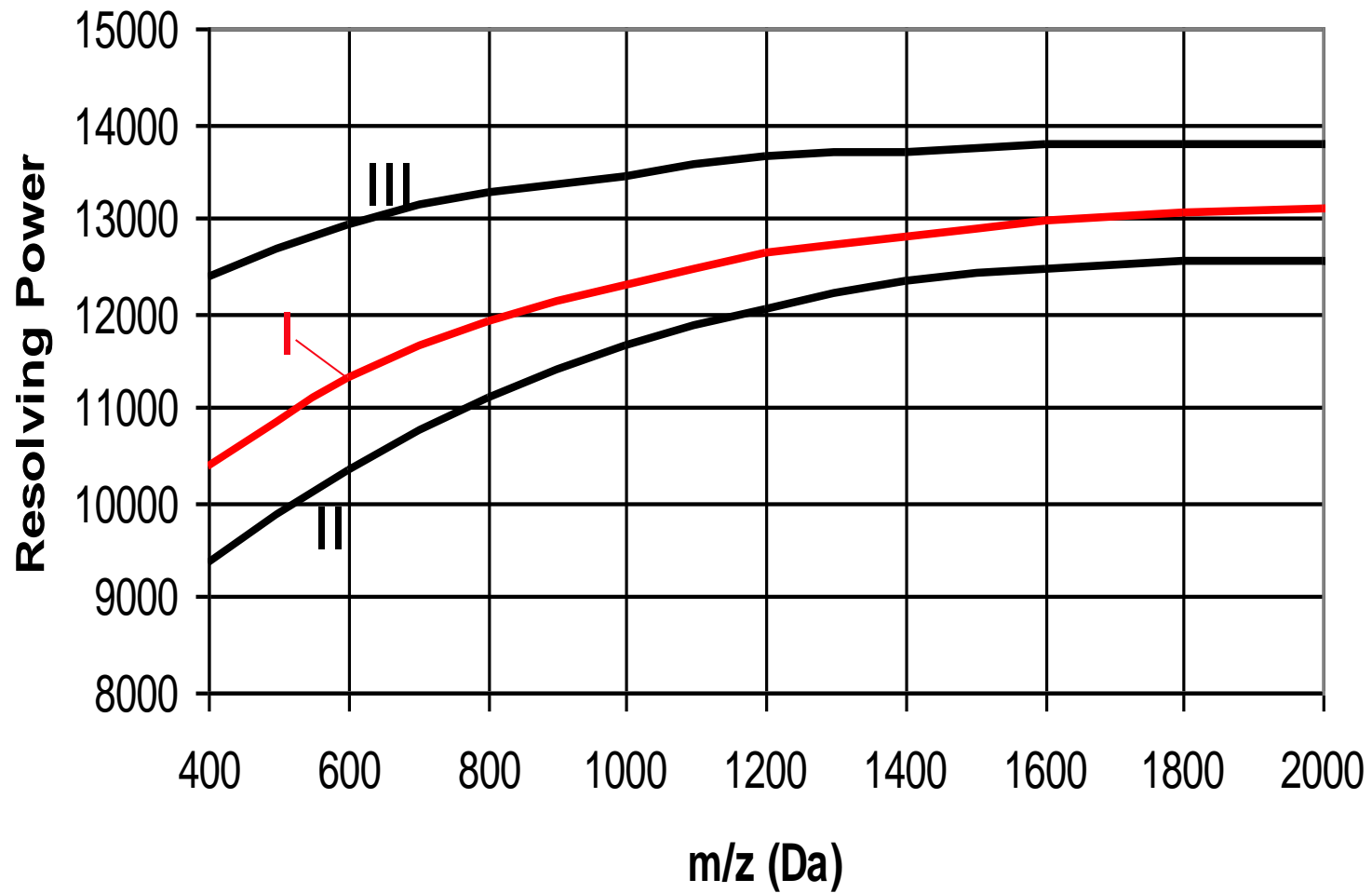
Time error, δt : $R_t = 2\delta t/t = 2\delta t v_n/D_e$

Trajectory error, δL : $R_L = 2\delta L/D_e$ **Not small!!!**

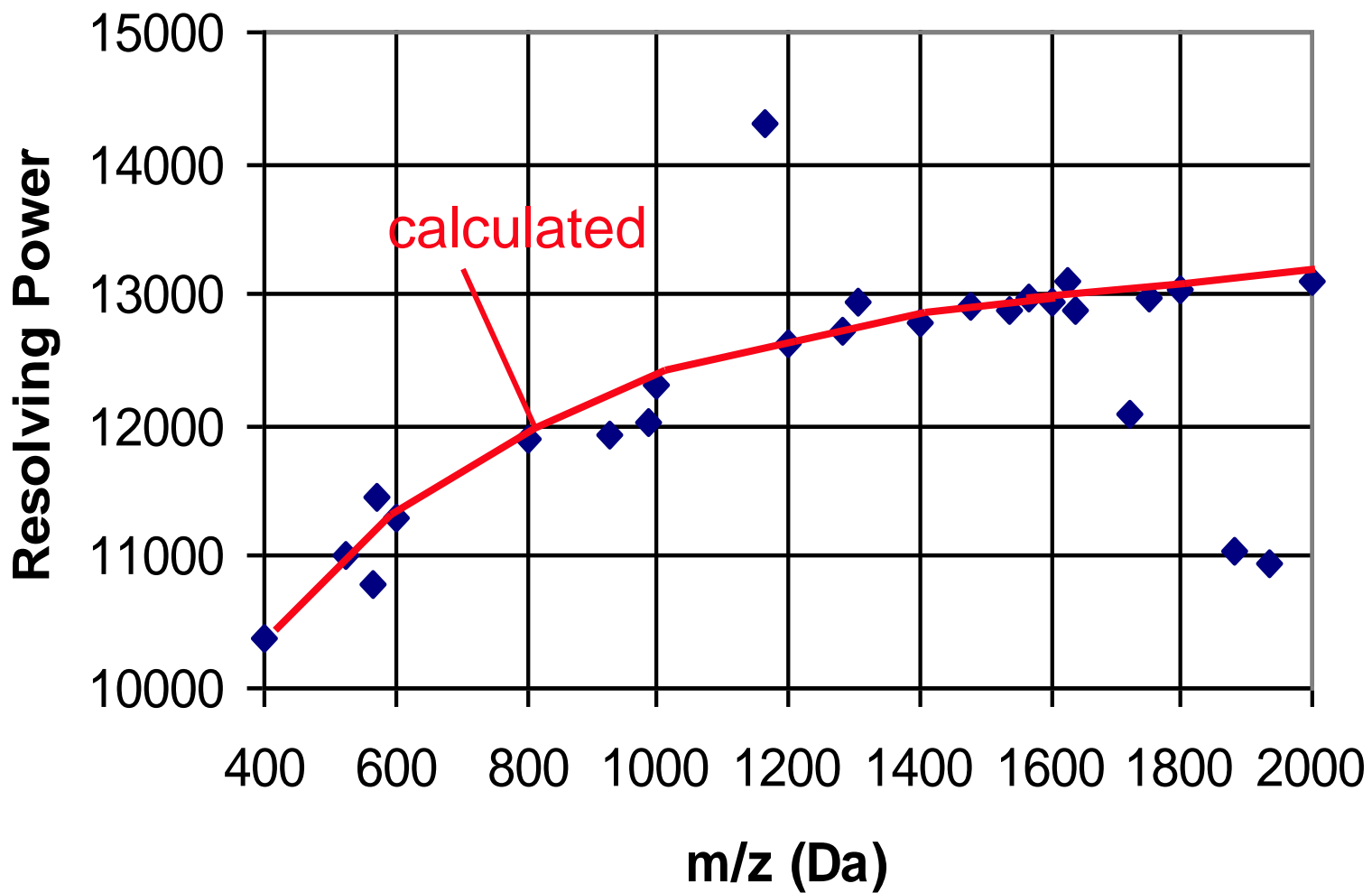
Voltage error, δV : $R_V = \delta V/V$

Resolving power:

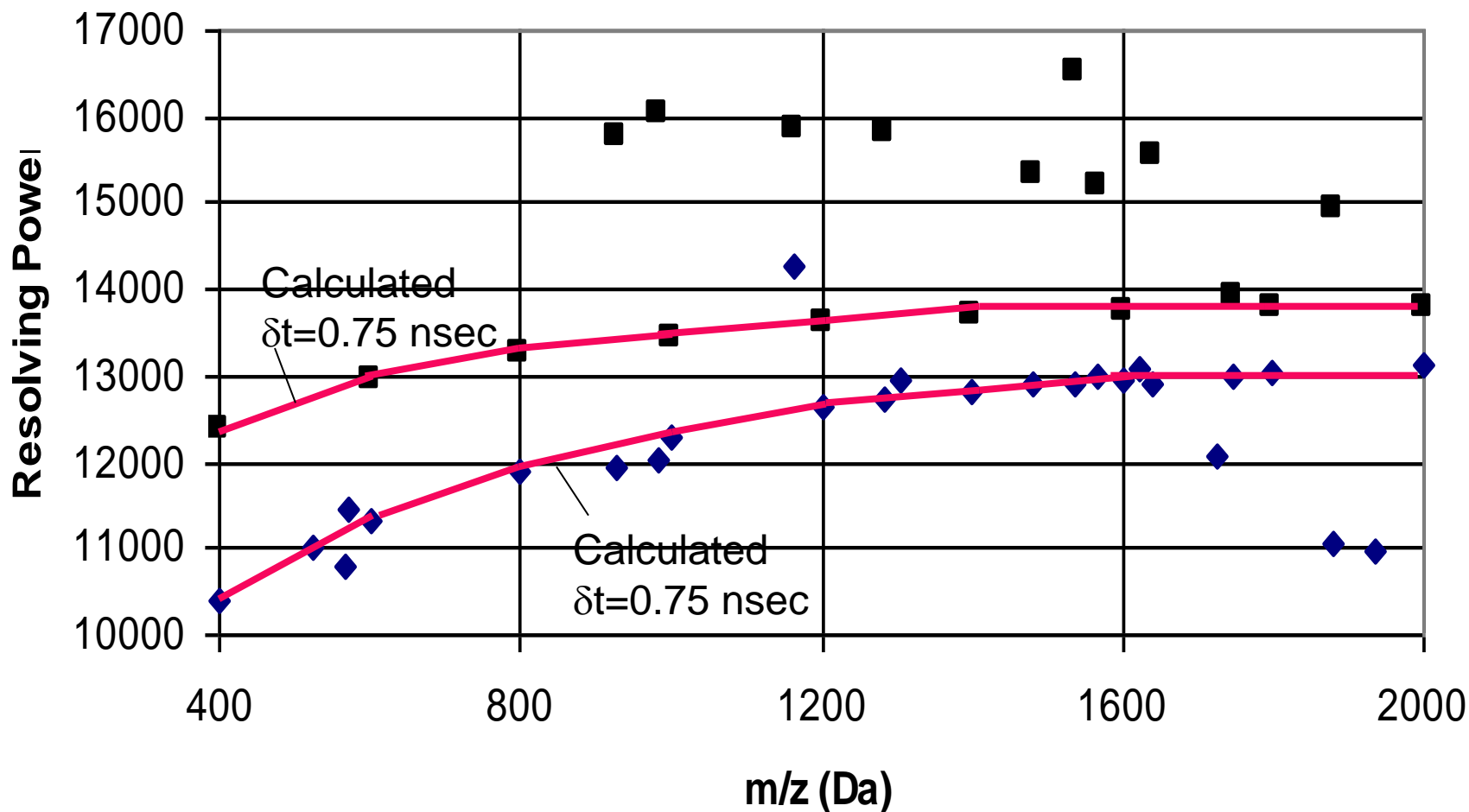
$$R^{-1} = [R_{s1}^2 + R_v^2 + R_t^2 + R_L^2 + R_V^2]^{-1/2}$$



Calculated resolving power for reflecting analyzer with $\delta V/V = 70$ ppm



Comparison of calculated resolving power with experimental results
With $\delta V/V=70$ ppm



Comparison of calculated resolving power with experimental results
 With $\delta V/V=70$ ppm. Measured \blacklozenge 5 μ channel plate \blacksquare ETP MagnetTOF™

*Contributions to relative peak width, $\Delta m/m$, with 1st and 2nd order velocity focusing (**size matters**)*

Initial position, δx : $R_{s1} = 2[(D_v - D_s)/2d_0y](\delta x/D_e)$

Initial velocity, δv_0 : $R_{v1} = (4d_0y/D_e)(\delta v_0/v_n)[(1 - (m/m^*)^{1/2})]$
 $R_{v2} = 2[2d_0y/(D_v - D_s)]^2 (\delta v_0/v_n)^2 = 0$
 $R_{v3} = 2[2d_0y/(D_v - D_s)]^3 (\delta v_0/v_n)^3$

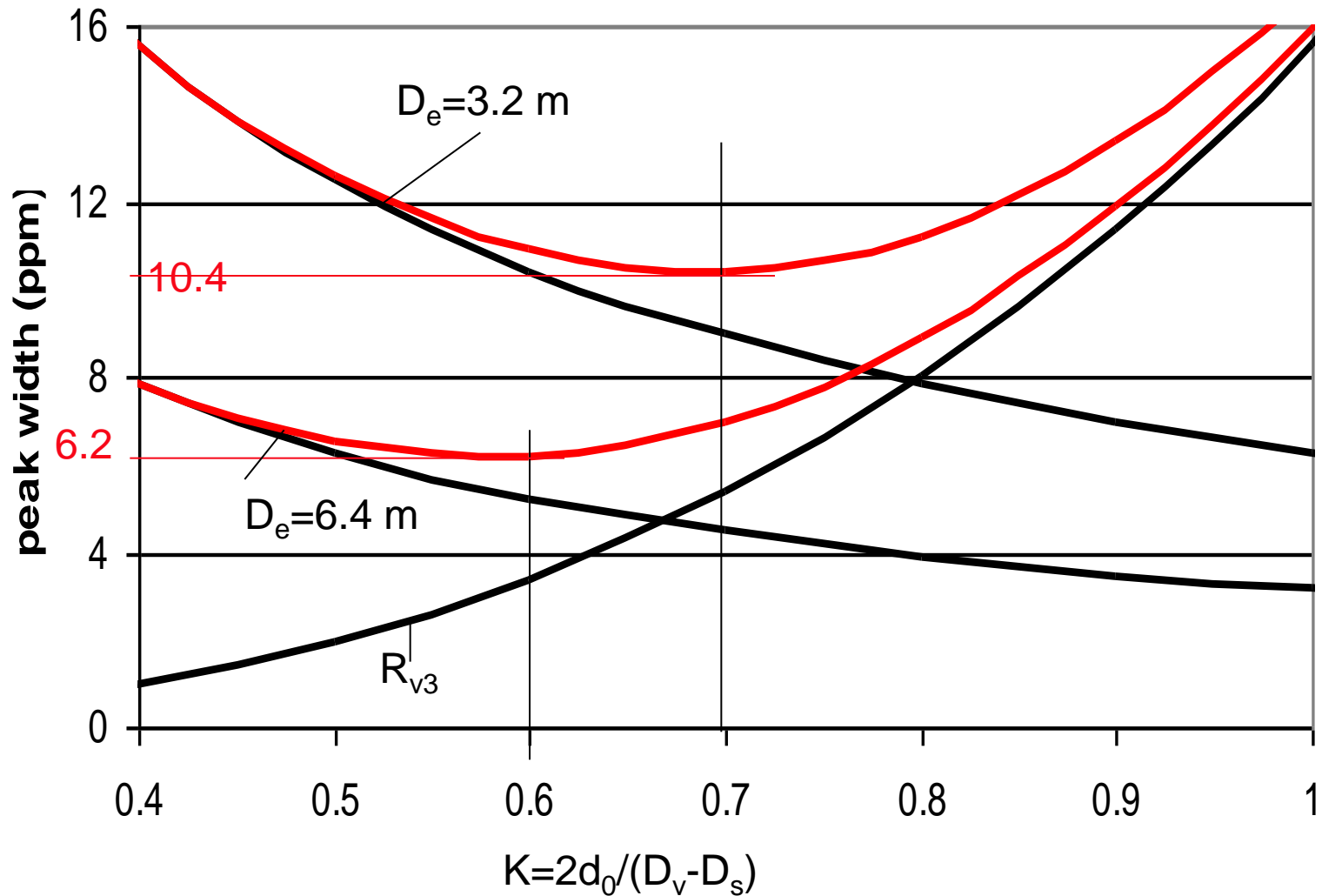
Time error, δt : $R_t = 2\delta t/t = 2\delta t v_n/D_e$

Trajectory error, δL : $R_L = 2\delta L/D_e$

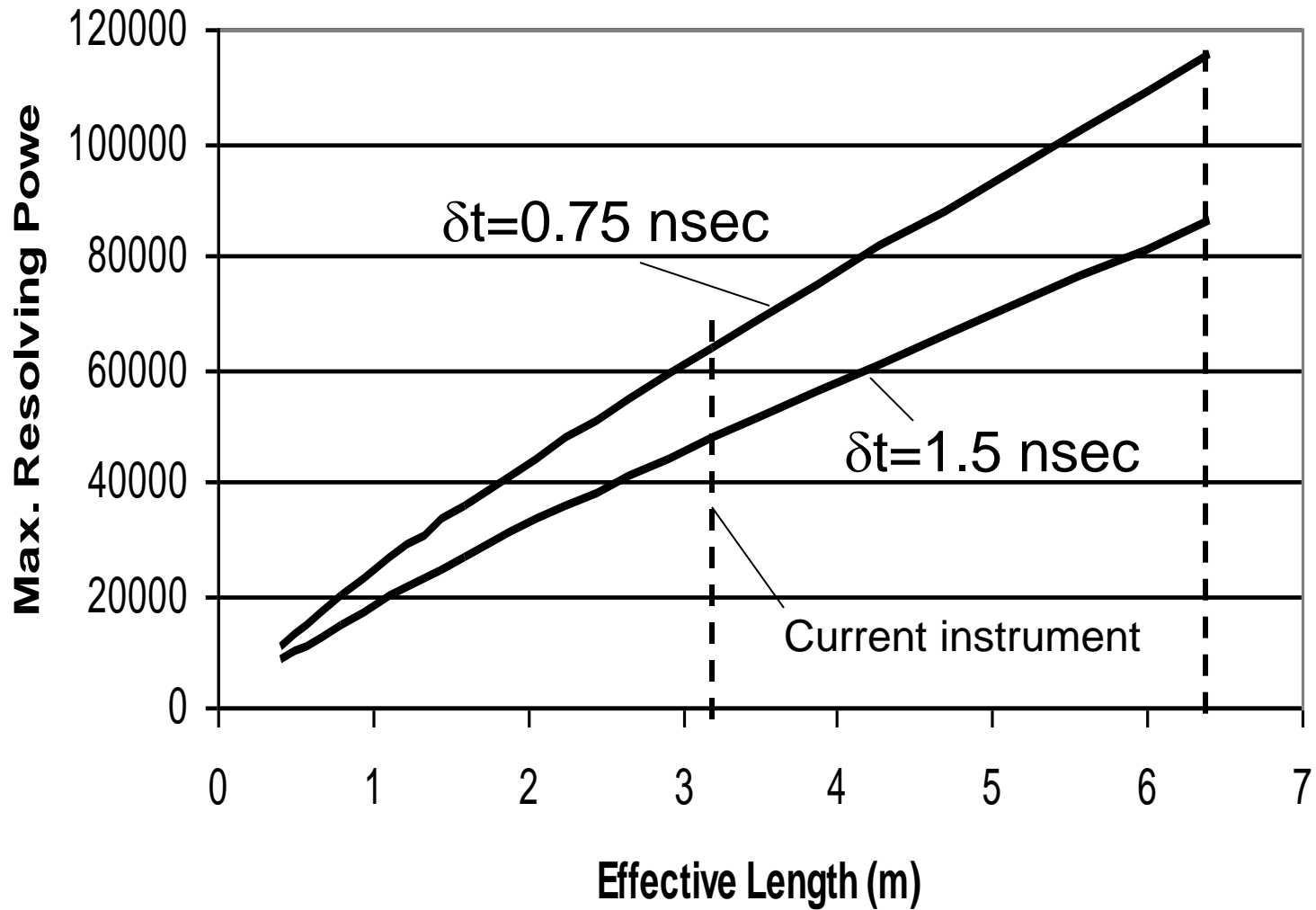
Voltage error, δV : $R_V = \delta V/V$

Resolving power:

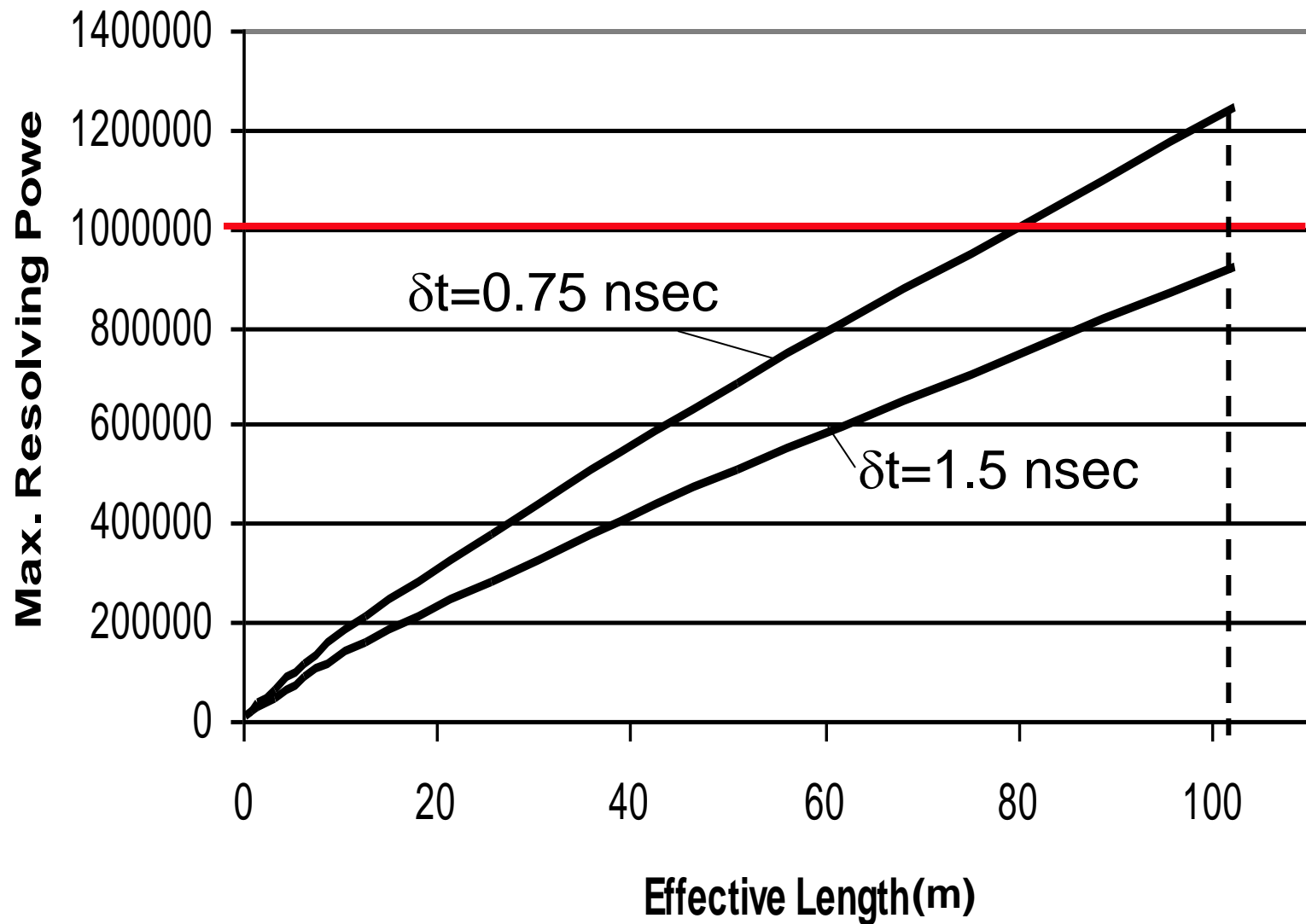
$$R^{-1} = [R_{s1}^2 + R_v^2 + R_t^2 + R_L^2 + R_V^2]^{-1/2}$$



Minimum peak width as function of focusing parameter K for effective Lengths of 3.2 and 6.4 m. Optimum values correspond to $dR/dK=0$, And is proportional to $D_e^{0.84}$ for these initial conditions.



Calculated maximum resolving power as function of effective length neglecting voltage error.



Calculated maximum resolving power as function of effective length neglecting voltage error.

Conclusions

- Resolving power of prototype reflecting analyzer is limited by voltage error or trajectory error
- If the total contribution of these two mass independent errors can be reduced to <10 ppm, then maximum resolving power of 50,000 is feasible with current prototype.
- Maximum resolving power is proportional to $D_e^{0.84}$
- 1,000,000 resolving power is theoretically feasible with an effective length of 100 m (physical length about 40 m)
- But!!!
- Errors independent of length must be less than 0.5 ppm (5 millivolts at 10 kilovolts)



The Virgins